

# TUT 5

System of ODE,

$$x_i = x_i(t)$$

$$(1) \begin{cases} x_1' = F_1(t, x_1, x_2, \dots, x_n) \\ x_2' = F_2(t, x_1, x_2, \dots, x_n) \\ \vdots \\ x_n' = F_n(t, x_1, x_2, \dots, x_n) \end{cases}$$

uniqueness and existence thm

Assume each  $F_i, \frac{\partial F_i}{\partial x_j} \quad i, j = 1, \dots, n$  are C's

in region  $R$  of  $x_1, \dots, x_n$  space s.t.  $\alpha < t < \beta,$

$x_1 < x_1 < \beta_1, \dots, x_n < \beta_n$ , let  $(t_0, x_1^0, x_2^0, \dots, x_n^0)$  be in  $R,$

then  $\exists$  an interval  $|t - t_0| < h$  in which  $\exists!$  solution

$$x_i = \phi_i(t)$$

We consider the  $n$  first order linear equation

has form

$$(2) \begin{cases} x_1' = p_{11}(t)x_1 + \dots + p_{1n}(t)x_n + g_1(t) \\ x_2' = p_{21}(t)x_1 + \dots + p_{2n}(t)x_n + g_2(t) \\ \vdots \\ x_n' = p_{n1}(t)x_1 + \dots + p_{nn}(t)x_n + g_n(t) \end{cases}$$

It is homogenous if all  $g_i(t) = 0$ , o.w. it's nonhomogenous

If we consider the system of (2), then we  
 the condition in uniqueness and existence then  
 change from  $\left[ F_i, \frac{\partial F_i}{\partial x_j} \text{ are cts} \right]$  to  
 $\left[ P_{ij}, g_i \text{ are cts} \right]$

Actually, a  $n$  order ODE can be written as  
 a system, consider,

$$a_n y^{(n)} + a_{n-1} y^{(n-1)} + \dots + a_0 y = g(t)$$

$$\text{let } x_1 = y$$

$$x_2 = y' = x_1'$$

$$\vdots$$

$$x_n = y^{(n-1)} = x_1^{(n-1)}$$

$$a_n x_n' = -a_{n-1} x_n - \dots - a_0 x_1 + g(t)$$

for (2), we write it as

$$\vec{X}' = P(t) \vec{X} + \vec{g}(t)$$

$$\vec{X} = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}, P(t) = \begin{pmatrix} P_{11} & \dots & P_{1n} \\ \vdots & & \vdots \\ P_{n1} & \dots & P_{nn} \end{pmatrix}, g(t) = \begin{pmatrix} g_1 \\ \vdots \\ g_n \end{pmatrix}$$

Consider the homogeneous case with constant

$$P_{ij}, \quad P(t) = A, \quad \vec{g}(t) = 0$$

$$\vec{x}' = A\vec{x}$$

Similarly to  $x' = ax$   
 $x = Ce^{at}$

Step ① find the eigenvalue of  $A \in M^{n \times n}(\mathbb{R})$

let them be  $r_1$  and  $r_2$ ,  $r_1 \neq r_2$ , real,

Step ② find the eigenvector corresponding to

$r_1; r_2$ , let them be  $\vec{\xi}_1$  and  $\vec{\xi}_2$ ,

Step ③,  $\vec{x} = C_1 \vec{\xi}_1 e^{r_1 t} + C_2 \vec{\xi}_2 e^{r_2 t}$  will be

a solution.

$$\text{If } r_1 = u_1 + v_1 i, \quad r_2 = \bar{r}_1 = u_1 - v_1 i$$

Step ② find the eigenvector corresponding to

$r_1, r_2$ , let them be  $\vec{\xi}_1 = \vec{a}_1 + b_1 i$ ,  $\vec{\xi}_2 = \vec{\xi}_1 = \vec{a}_1 - b_1 i$

Step ③, Consider  $\vec{\xi}_{11} e^{r_1 t} = \vec{\xi}_1 e^{u_1 t} \cdot e^{v_1 t i}$

$$= \vec{w} + \vec{z} i$$

then  $\vec{x} = C_1 \vec{w} + C_2 \vec{z}$  is a solution.

Some result will be obtained if you use

$$\vec{\xi}_2 \cdot e^{r_2 t}$$

If  $r_1 = r_2 \in \mathbb{R}$ , and  $A$  is not self-adjoint,

Step ② find the eigenvector of  $r_1$ , let it

be  $\xi_1$

Step ③, it is different from the 1-dim case,

another solution is not  $\xi_1 t e^{r_1 t}$  x!!!!

$$\text{let } x^{(1)}(t) = \vec{\xi}_1 e^{r_1 t},$$

$$x^{(2)}(t) = \vec{\xi}_1 t e^{r_1 t} + \vec{\eta} e^{r_1 t}$$

$$\text{Lmb: it is } \vec{x}' = A\vec{x},$$

$$\text{we will have } t e^{r_1 t} (r_1 \vec{\xi}_1 - A\vec{\xi}_1) + e^{r_1 t} (\vec{\xi}_1 + r_1 \vec{\eta} - A\vec{\eta}) = 0$$

$$\therefore \begin{cases} r_1 \vec{\xi}_1 - A\vec{\xi}_1 = 0 \\ \vec{\xi}_1 + r_1 \vec{\eta} - A\vec{\eta} = 0 \end{cases}$$

we solve  $\vec{\eta}$ ,

$$\text{so } \vec{x} = \vec{x}^{(1)} + \vec{x}^{(2)}$$

Problem:

$$\textcircled{1} \quad x' = \begin{pmatrix} 1 & -2 \\ 3 & -4 \end{pmatrix} x$$

Ans. let  $r$  be eigenvalues

$$\begin{vmatrix} 1-r & -2 \\ 3 & -4-r \end{vmatrix} = 0$$

$$(r-1)(r+4) + 6 = 0$$

$$r = -2 \text{ or } -1$$

If  $r = -2$ , let  $\vec{x}_1$  be its vector,

$$\begin{pmatrix} 1+2 & -2 \\ 3 & -4+2 \end{pmatrix} \begin{pmatrix} x_1^1 \\ x_1^2 \end{pmatrix} = 0$$

Consider  $\begin{pmatrix} 3 & -2 \\ 3 & -2 \end{pmatrix} \rightsquigarrow \begin{pmatrix} 3 & -2 \\ 0 & 0 \end{pmatrix}$

$$3x_1^1 - 2x_1^2 = 0$$

$$\vec{x}_1 = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$$

If  $r = -1$ ,  $\vec{x}_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$$\therefore \vec{x} = c_1 \begin{pmatrix} 2 \\ 3 \end{pmatrix} e^{-2t} + c_2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-t}$$

$$\textcircled{2} \quad \vec{X}' = \begin{pmatrix} 1 & 2 \\ -5 & -1 \end{pmatrix} \vec{X},$$

Ans:  $\begin{vmatrix} 1-r & 2 \\ -5 & -1-r \end{vmatrix} = 0$

$$(r-1)(r+1) + 10 = 0$$

$$r = \pm 3i$$

If  $r_1 = 3i$ , let  $\vec{z}_1$  be the eigenvector,

$$\begin{pmatrix} 1-3i & 2 \\ -5 & -1-3i \end{pmatrix} \rightsquigarrow \begin{pmatrix} 5-15i & 10 \\ -5+15i & (-1-3i)(1-3i) \end{pmatrix}$$

$$\rightsquigarrow \begin{pmatrix} 0 & 0 \\ -5+15i & -10 \end{pmatrix} \rightsquigarrow \begin{pmatrix} 0 & 0 \\ -1+3i & -2 \end{pmatrix}$$

$$\hookrightarrow \vec{z}_1 = \begin{pmatrix} -1-3i \\ 5 \end{pmatrix}$$

$\hookrightarrow$  consider  $\begin{pmatrix} -1-3i \\ 5 \end{pmatrix} e^{(3i)t} = (\cos 3t + i \sin 3t)$

$$= \left( \begin{pmatrix} -1 \\ 5 \end{pmatrix} + \begin{pmatrix} -3 \\ 0 \end{pmatrix} i \right) (\cos 3t + i \sin 3t)$$

$$= \left[ \begin{pmatrix} -1 \\ 5 \end{pmatrix} \cos 3t + \begin{pmatrix} 3 \\ 0 \end{pmatrix} \sin 3t \right] + i \left( \begin{pmatrix} -3 \\ 0 \end{pmatrix} \cos 3t + \begin{pmatrix} -1 \\ 5 \end{pmatrix} \sin 3t \right)$$

$$\therefore \vec{X} = C_1 \left( \begin{pmatrix} -1 \\ 5 \end{pmatrix} \cos 3t + \begin{pmatrix} 3 \\ 0 \end{pmatrix} \sin 3t \right) + C_2 \left( \begin{pmatrix} -3 \\ 0 \end{pmatrix} \cos 3t + \begin{pmatrix} -1 \\ 5 \end{pmatrix} \sin 3t \right)$$

$$(3) \quad x' = \begin{pmatrix} 3 & 1 \\ -4 & -1 \end{pmatrix} \vec{x}$$

Ans: let  $r$  be eigenvalues,

$$\begin{vmatrix} 3-r & 1 \\ -4 & -1-r \end{vmatrix} = 0$$

$$(r-3)(1+r) + 4 = 0$$

$r = 1$  (repeated)

the corresponding eigenvectors are  $\vec{x}_1$ ,

$$\begin{pmatrix} 2 & 1 \\ -4 & -2 \end{pmatrix} \rightsquigarrow \begin{pmatrix} 2 & 1 \\ 0 & 0 \end{pmatrix}$$

$$\therefore \vec{x}_1 = \begin{pmatrix} 1 \\ -2 \end{pmatrix}$$

let  $\vec{\eta}$  s.t.  $\vec{x}_2 = \vec{x}_1 t e^{rt} + \vec{\eta} e^{rt}$

sub  $x_2$  into  $x' = \begin{pmatrix} 3 & 1 \\ -4 & -1 \end{pmatrix} \vec{x} = A\vec{x}$

$$\vec{x}_1 e^{rt} + \vec{x}_1 r t e^{rt} + \vec{\eta} r e^{rt} = A \vec{x}_1 t e^{rt} + A \vec{\eta} e^{rt}$$

$$t e^{rt} (\vec{x}_1 r - A \vec{x}_1) + e^{rt} (\vec{x}_1 + \vec{\eta} r - A \vec{\eta}) = 0$$

$$\therefore \begin{cases} \vec{x}_1 r - A \vec{x}_1 = 0 \\ \vec{x}_1 + \vec{\eta} r - A \vec{\eta} = 0 \end{cases}$$

$$\hookrightarrow \begin{cases} \vec{x}_1 r - A \vec{x}_1 = 0 \\ \vec{x}_1 + \vec{\eta} r - A \vec{\eta} = 0 \end{cases}$$

$$(A - I r) \vec{\eta} = \vec{x}_1$$

$$\left( \begin{array}{ccc|c} 3 & -1 & 1 & 1 \\ -4 & -1 & -1 & -2 \end{array} \right) \rightsquigarrow \left( \begin{array}{ccc|c} 2 & 1 & 1 & 1 \\ -4 & -2 & -2 & -2 \end{array} \right) \rightsquigarrow \left( \begin{array}{ccc|c} 2 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

$$2x_1 + x_2 = 1$$

$$x_2 = 1 - 2x_1$$

$$\hookrightarrow \vec{\eta} = \begin{pmatrix} k \\ 1 - 2k \end{pmatrix}$$

You can choose  $k$  to be all values of  $\mathbb{R}$ ,

Choose  $k = 0$ ,

$$\vec{x} = \vec{x}_1 + \vec{x}_2$$

$$= c_1 \begin{pmatrix} 1 \\ -2 \end{pmatrix} e^t + c_2 \begin{pmatrix} t \\ -2t + 1 \end{pmatrix} e^t$$